

INOVANCE

H5U Series PLC

High performance, compact, EtherCAT-enabled PLC



- Compact footprint
- PLCopen-compliant axis control
- Simulation mode for offline debugging
- Real-time fieldbus



H5U: high performance PLC

Programming

- Supports function block and function for encapsulation, code reusability, and scalability
- Efficient and easy-to-use ladder diagram programming, supporting graphic block instructions
- User-defined variable programming with intuitive programming input assistant

Commissioning

- Simulation mode
 - PLC programs
 - Axis control
 - Local I/O
 - Serial and Ethernet comms
- High-resolution trace tool
- Program upload/download and firmware upgrade (only available with SD card)
- Axis interface for easy test and monitoring

I/O configuration

- Main unit with 16 inputs and 14 outputs, including high-speed I/Os
- Supports up to 16 GL10 (AM600 series) local expansion modules
- Remote GR10 I/O modules can be connected as EtherCAT slaves

Please note: refer to AM600 catalogue for more detail about our remote I/O modules

Communications

- Supports 72 EtherCAT slaves
- 1 CAN interface: CANopen and CANlink master/slave
- 1 RS485 interface: Modbus RTU master/slave
- 1 Ethernet connection supports Modbus TCP and socket programming instructions

Motion control

- EtherCAT: 32-axis PTP motion control
- PLCopen-compliant axis control
- Local pulse and EtherCAT axis share the same motion control instructions
- Axis group for lineal and circular interpolation
- CAM tables functionality
- 4× high speed pulse output channels, to control stepper motors
- Able to control servo drive via CANopen



Scan for more information

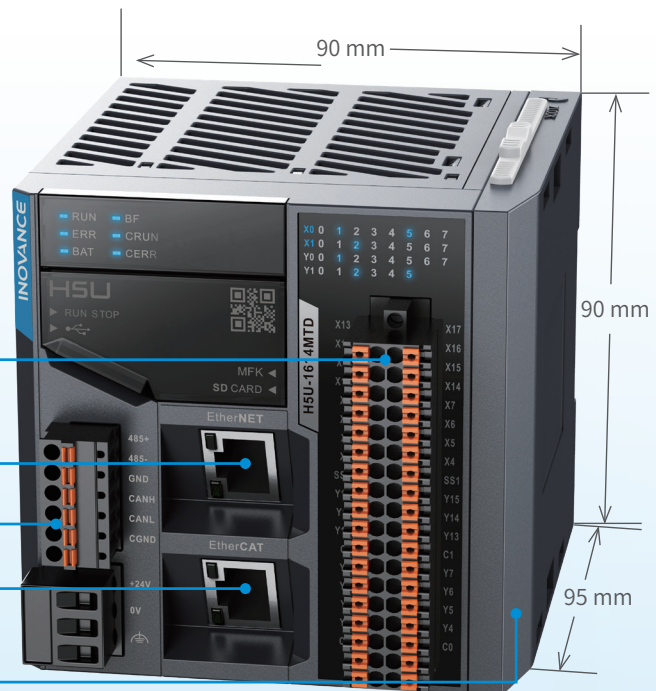
Built-in I/Os
16 DI (with 4×200 kHz channels)
14 DO (with 4×200 kHz channels)

Ethernet interface

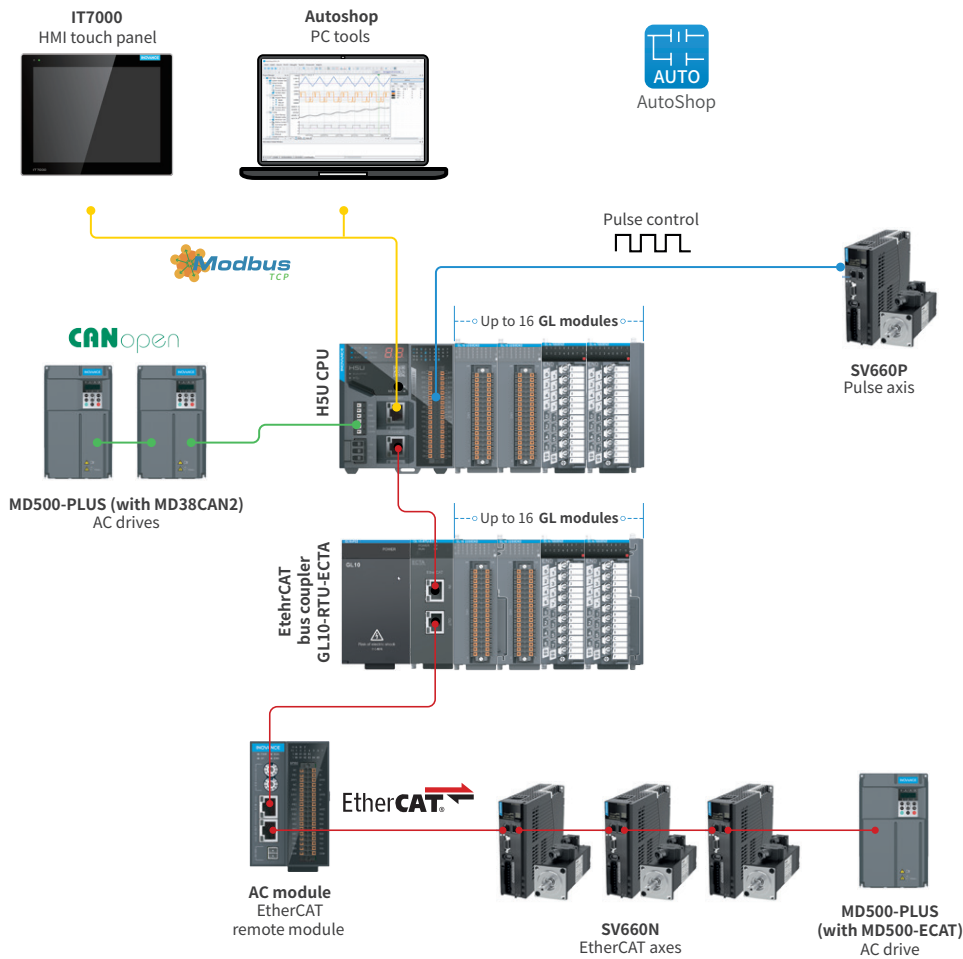
RS485/CAN port

EtherCAT interface

16 extension modules (local bus)



H5U - application topology



General specifications

Model	H5U-1614MTD-INT
Axis capacity	A total of 32 synchronised axes is possible. This can be a max. of 32 EtherCAT axes ^[1] , or a combination that includes a max. of four pulse control axes
Communication specifications	EtherCAT: max. 72 EtherCAT slaves ^[2] (including synchronised axes)
	Ethernet: Modbus TCP, socket programming
	CAN: supports CANlink and CANopen (only supports CANopen for axis control)
Program capacity	200 K-step user program
Data capacity	2 MB user-defined variables, of which 256 KB supports power failure retention Approx. 150 KB soft elements, of which 145 KB supports power failure retention
Programming language	LD, SFC, supporting function block/ function (LD)
High-speed I/Os	4×200 kHz high-speed inputs (2 encoder counting) 8×200 kHz high-speed outputs (4-axes pulse output)
General I/Os	16 sink (NPN)/ source (PNP) inputs and 14 sink (NPN) outputs (including high-speed I/Os)
Module expansion	16 local modules, remote modules can be connected as EtherCAT slaves
Power input	+24V DC
Other interfaces	USB SD card
Dimensions (W×H×D)	83 mm×90 mm×95 mm

Note:

[1] Synchronised axes

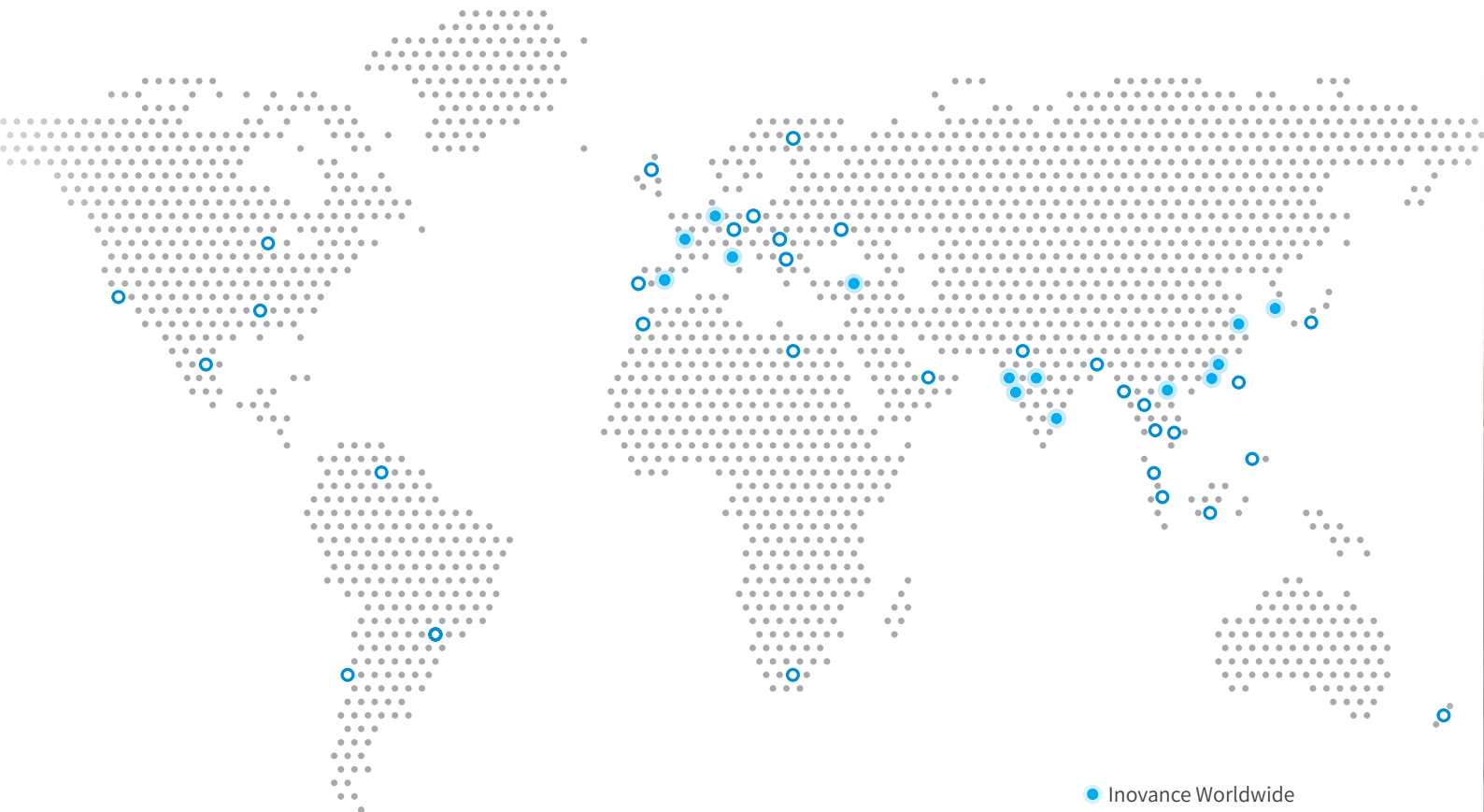
[2] EtherCAT slaves include I/Os and synchronised and non-synchronised axes

For more information, please contact our local offices.



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